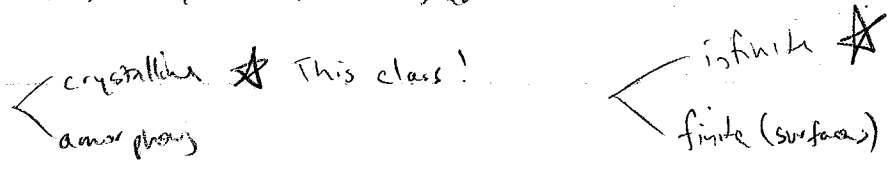


- Introduce myself
- Introduction of class.
- Syllabus:
 - textbook (Chap 1-8, part 9, part of 14)
 - HW
 - exam

Need substitute for 2 assignments!

What is a solid? resist shear



Crystal " periodicity (atoms)



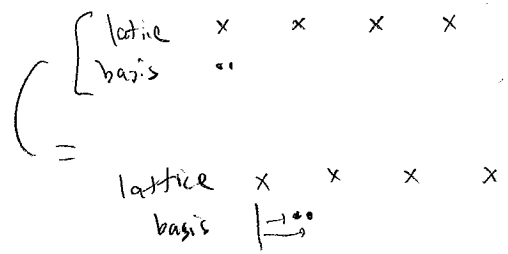
what about ?

period yes, is crystal

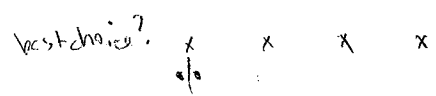
lattice details of periodicity (abstract pts)

basis details of atoms that are found at the lattice pts

Note lattice choice is not unique



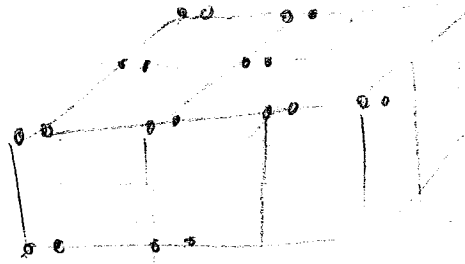
(but some choices are better than others)



* basis is symmetric, possibly best choice.

Symmetry! Mathematical techniques for analyzing symm = Group Theory (beyond this class)

3D



← could be crystal

lattice = "simple cubic"

basis?
 atom 1 at $(0, 0, 0)$
 atom 2 at $(0, \frac{1}{4}, 0)$

— Vectors that join lattice pts

Lattice vectors - Defn: Any vector which causes (infinitely) crystal to be unchanged after translation (translates into itself)

What are some L.V.s for cube above?

Primitive lattice vectors: (1) the 3 ones (non unique choice) that form basis for all L.V.s

Example: for cube above,

$$\vec{a}_1 = (1, 0, 0)$$

$$\vec{a}_2 = (0, 1, 0)$$

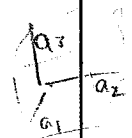
$$\vec{a}_3 = (0, 0, 1)$$

(2) and one as "small as possible" (a consequence of (1), really. See Fig 3 pg 5)

Small as possible: defined by volume of space of parallelepiped defined by $\vec{a}_1, \vec{a}_2, \vec{a}_3$

$$\text{Volume} = |\vec{a}_1 \cdot (\vec{a}_2 \times \vec{a}_3)|$$

$$\text{any lattice vector } \vec{R} = n\vec{a}_1 + m\vec{a}_2 + l\vec{a}_3$$



Basis vectors - vectors from origin to basis atoms
 ↳ position of lattice point

$$j \text{ atoms: } \vec{r}_j = x_j \vec{a}_1 + y_j \vec{a}_2 + z_j \vec{a}_3$$

if desired, can pick origin so

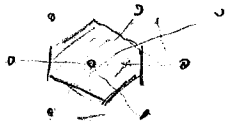
$$x_j, y_j, z_j \text{ all between } 0 \rightarrow 1.$$

Wigner-Seitz cell

= a "primitive lattice cell" = parallelepiped formed by $\vec{a}_1, \vec{a}_2, \vec{a}_3$

↳ How many will there be in a given volume?
 Answer: the same as # of lattice pts.

- the WS cell = a specially chosen primitive cell



region enclosed by perpendicular bisectors.

class 1

class 2

primitive basis

- a basis that's based on a set of primitive L.V.s.

Symmetry, again

1) translation (already discussed)

2) rotation

defined by axis about which x'tal can be rotated

simple cubic: $90^\circ, 180^\circ, 270^\circ$ about x
 C_4, C_2, C_4^3
 C_2^2

also about y, z.

Notation... let's not bother (?)

$$C_{4x} = 270^\circ \text{ rotation about } x\text{-axis}$$

$$C_{4x} = 90^\circ \text{ rotation}$$

3) reflection: defined by plane about which x'tal atoms can be reflected σ_x

4) combo: rotation + reflection labeled "S"

5) inversion: if pt exists through which all atoms can be inverted "I"

group of symmetries together form a "group"

Symmetry of crystal vs symmetry of lattice